



Analysis of the Floating Car Data of Turin Public Transportation system: first results

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PRIN PROJECT: URBAN GEOmatics for Bulk Information Generation, Data Assessment and
Technology Awareness



MINISTERO DELL'ISTRUZIONE, DELL'UNIVERSITA' E DELLA RICERCA

Floating Car Data (FCD)

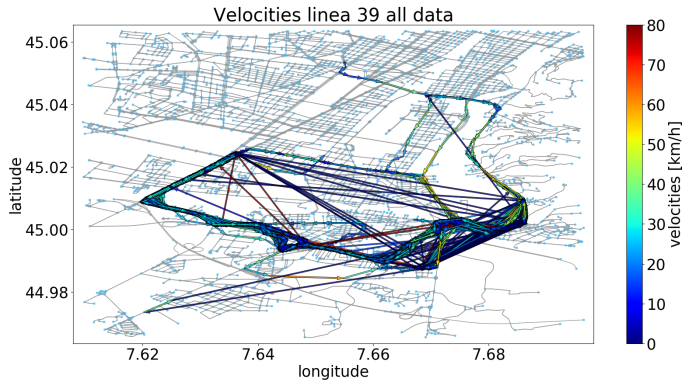
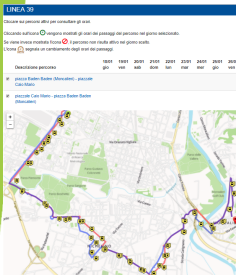
- ▶ The **Floating Car Data (FCD)** of **Turin Public Transportation** system were acquired by every vehicle of the fleet through its On Board Unit (OBU) in the **month of April 2017**, with a **variable time interval** (difference of several seconds)
- ▶ The **FCD** are provided in the **CSV** format and include the **geographical coordinates** along with a **set of attributes** (vehicle code, line code, turn, timestamp, ecc.)
- ▶ The original file is very **heavy** (2.19 GB, **30·000·000**) and it was converted in a **database** through a Python script based on the sqlite3 and pandas libraries

Velocity analysis

- ▶ The **FCD** were **analysed** for **lines**, then for **vehicles** and finally they were **chronologically ordered**
- ▶ For every line of the transportation network:
 - ▶ the *Vincenty* formula was used to compute the **planimetric displacement** Δs between **two positions** of the specific vehicle in two **consecutive time moments**
 - ▶ the **velocities** were computed as $v = \frac{\Delta s}{\Delta t}$
- ▶ The computed **velocities** were represented as **arrows** and plotted on top of the **Turin drive network graph**, automatically downloaded from Open Street Map
- ▶ Before proceeding with the time analysis, the **outliers** were **removed** by eliminating all the records not statistically significant ($\Delta t > 99.5^{th}$ percentile & $\Delta t < 0.5^{th}$ percentile & $v > v_{mean}$)

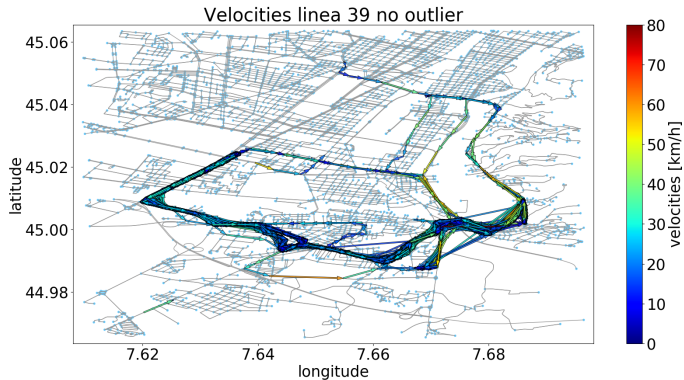
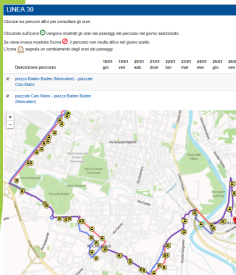
Line 39: velocities

After the **outlier removal**, the reconstructed path follows more closely the actual line route: the **longest arrows**, probably due to the bus routes from and to the depot, are **eliminated**



Line 39: velocities

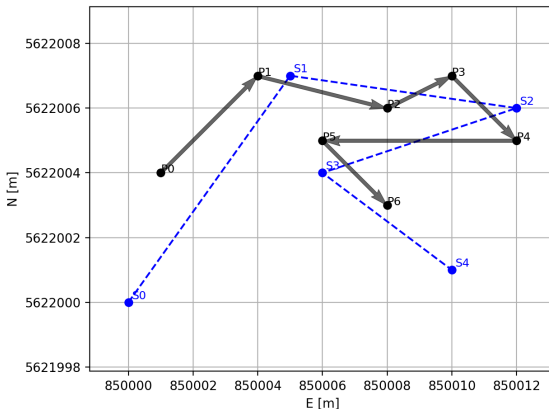
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FCD projection to line networks

A preliminary strategy was implemented to **assign** the **velocities** to the **line network topology**:

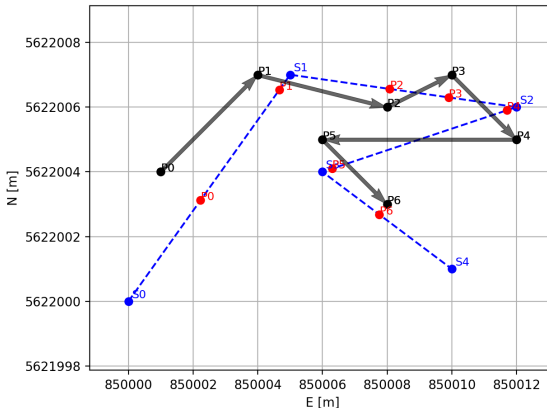
- ▶ for **every FCD point**, the **closest tree** of the specific line network is selected



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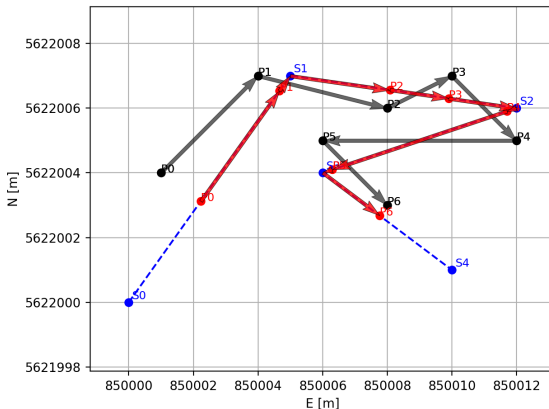
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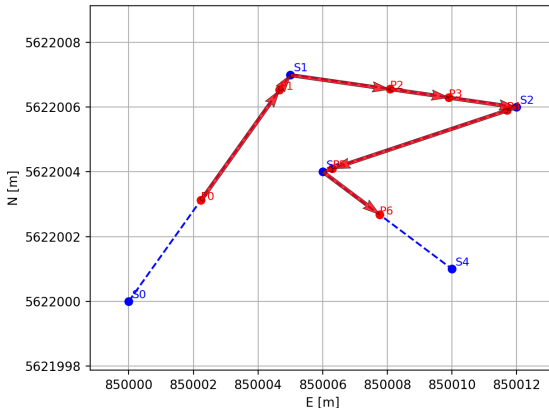
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FCD projection to line networks

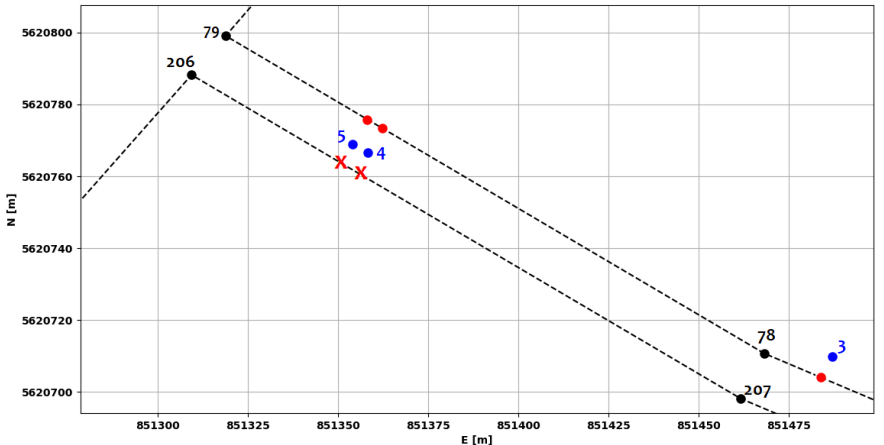
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- ▶ for **every FCD point**, the **closest tree** of the specific line network is selected



Topological issues

Topological issues occur when the FCD point is located in a segment in which the **distance between two** (or more) **trees** is **comparable** to the **GNSS measurement errors**



Topological issues

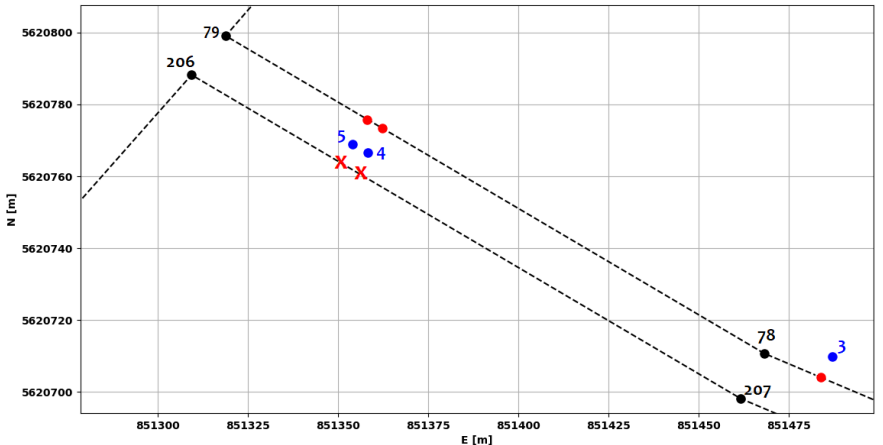
A possible solution is to consider:

- ▶ the **cardinality information** contained in the **line network**
- ▶ the **temporal information** contained in the **FCD**

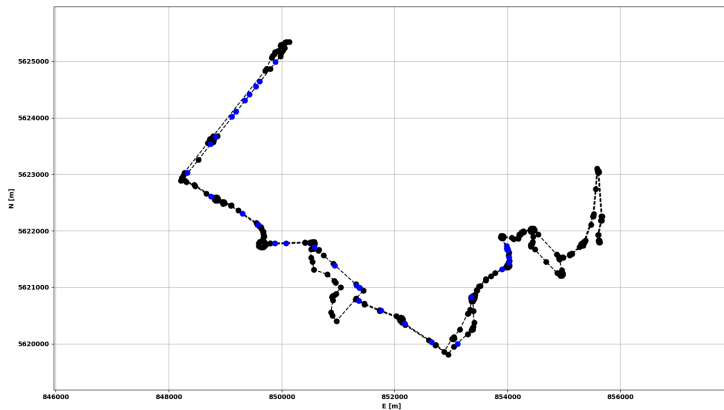
Select the segment closest to the previous selected tree

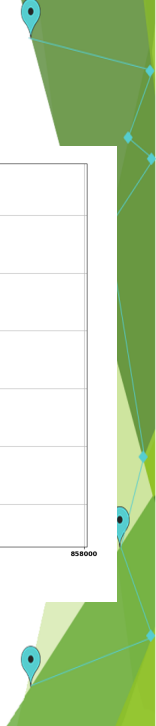
Topological issues

It is rather improbable that the FCD **point 4** and **point 5** may be assigned to the **tree 206-207** of the network, since the vehicle was located in the **tree 77-78** few moments before



FCD projection to line networks





Conclusions and further developments

A **general methodology** able to **analyse** the huge amount of information contained in **Transport Big Data** has been developed

Necessary further developments:

- ▶ refine the outlier removal process in order to all the **velocities not referable** to the **actual path** of the **lines**
- ▶ to **test** the developed **topological procedure** on **all** the **velocity data**, by checking the **effective reliability** and **real-time feasibility** of the designed methodology
- ▶ to **compute** the **impedance maps** and deliver the corresponding **metadata**
- ▶ extend the developed methodology to the other cities of the PRIN

Thank you for your kind attention!